

## Bistatic Space Borne Radar for Early Warning

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### ABSTRACT

*The Bistatic Radar architecture, with early warning capability, has been analyzed considering the Tactical Ballistic Missiles (TBM), cruise missile and aircraft, as preferred threats. This study is addressed to analyze the requirements and a proper design of a space borne Bistatic SAR (BSAR) with the relevant performance. The bistatic solution has been considered as a preferred one due to the good immunity to potential jammer present on the theatre area, allowing also a reduced value of peak transmitter power, permitting to utilize quite all the temporal interval for the signal transmission without interruption during the receiving phase. The BSAR technique permits to increase the resolution in order discriminate closely targets.*

*In addition this paper investigates the imaging of an isolated fast moving pointing object (MPO) and the clutter cancellation needed in presence of fixed terrain/sea background (feature expected in the realistic situation of an object moving over a terrain or over the ocean).*

### 1. INTRODUCTION

In view of this growing potential threats to Europe this study is addressed to analyze the system architecture and the radar characteristics that can give an early warning capability for a suitable immediate defense reaction.

In particular this study addresses the problem of requirements description and design of a space borne bistatic SAR. The transmitter will be on board one or more geo-stationary or HEO satellites while the receiver only on board the LEO satellite constellation. In this solution the LEO satellite constellation will be simpler and lighter due to the absence of the transmitter on board each LEO satellite. The drawbacks, on this solution, are the range between the transmitter and the illuminated target, the lower reliability in case of a transmitter failure. The BSAR requires synchronization between the transmitter satellite and the

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receivers on board the LEO satellite constellation. Therefore a direct communication link between the transmitter and the receiver is necessary in order to measure the frequency and the phase of the received signal referred to the transmitted signal. The imaging of an isolated moving point like object and the clutter cancellation technique are analyzed considering the realistic situation of a target moving over a terrain or over an ocean area.

## 2. SYSTEM REQUIREMENTS

The wide area coverage has an extension of about 2200 km \* 9400 km. Within this area coverage are defined the theatre regions (*access area*) that will have an extension of about 1500 km \* 1500 km. An 'a priori' knowledge of which theatre area has to be covered will permit to concentrate the surveillance of the satellite constellation only on this specific area. After detection and track extraction of a threat within the theatre area the system must be capable to maintain the track of the detected target as well to maintain the surveillance task on the assigned crisis area. The system availability required is 80 % with a reconfiguration capability (for a new crisis area) within 24 hours.

The threats to be detected and engaged are:

- TBM;
- Cruise missile;
- Aircraft.

The missile and aircraft threats have been defined in terms of radar parameters, in order to select the best radar solution for the satisfaction of the requirements as follows:

- Target RCS  $0.2 \text{ m}^2$ . The Radar Cross Section will fluctuate according to Swerling case 1;
- Altitude within 50 Km- 400 Km for TBM, 200 m- 400 m for cruise missile and 200 m-10 Km for aircraft;
- Maximum range for TBM 3500 km. Time of flight for TBM 1÷15 minutes. Average absolute velocity for TBM  $\leq 2.5 \text{ km/sec.}$ ;
- Delivery to ground based radar of the target position within a basket of  $1^\circ * 1^\circ * 1 \text{ km}$ . For tracking requirements (plot association, track formation) the resolution will be within 1 km;
- Presence of jamming on board and on ground enemy radar;
- Ground/Sea clutter level to be considered.

Two configurations have been preliminary considered and envisaged as potential candidates for a design base:

- Transmitter on board geo-stationary satellite and receiver only on board the satellite constellation;
- Transmitter and receiver on board each satellite on the constellation.

As stated in the introduction the first solution (bistatic) has been selected as a preferred one considering that also if the second solution has the advantage to be more reliable (e.g. if one TX fails the mission is not completely jeopardized) there is a drawback in terms of cost due to the transmitter on board each satellite. The constraint on the system configuration (radar and satellite constellation) is the minimization of the number of satellite (for a realistic and feasible design). They should be as low as possible (e.g. less than 100 satellites should be a goal) for the reduction of cost, maximization of utilization with affordable management and maintenance. This constraint, considering the theatre area of 1500 km \* 1500 km (very wide swath capability), has suggested the utilization of the following techniques:

- Use of large antennas;
- Beam forming and phased array;
- SCANSAR.

Moreover we can notice that:

- The reason for the selection of the bistatic SCANSAR solution is a good trade-off between number of satellites needed and the LEO constellation lightness including solar arrays due to the transmitter absence. It has to be considered that a sophistication for the transmitters on HEO is, in any case, unavoidable. In addition the bistatic geometry permits to utilize all the temporal interval for the transmitter without interruption during the receiving phase. It is possible to utilize CW signal (coded) with lower peak power and higher radiometric performance;
- The Signal to Noise ratio (SNR) is a critical parameter, considering the satellites geometry (range) and the limited value of the radar cross section of the targets. In addition the SNR is strongly correlated with the power density on the target and therefore to the swath dimension (TX and RX antennas gain);
- The theatre area (swath size) is too much extended to be covered with a reasonable number of satellites;
- The resolution requirements, for the target spatial identification, are in good agreement with the beam dimension during acquisition and also during tracking, due to the improvement factor, related to the implementation of the Synthetic Aperture concept (SAR), taking into account the integration of a certain number of pulses (defined by the time needed to generate the synthetic antenna referred to the p.r.f.).

In order to arrive to a feasible solution, few constraints have been assumed, considering the present and future (next 10 years) state of the art technology:

- The maximum available transmitter power can not be greater than 75 KW for practical reasons;
- The antenna dimension has been limited to 15 m \* 15 m (limited to these values by mechanical problems);
- A frequency utilization within the L band (1÷2 GHz) has been selected as a good trade-off between loss and components availability (antenna and transmitter).

### **3. BISTATIC GEOMETRY**

In order to analyze the constraint related to the **Range resolution** a particular bistatic intercept geometry is shown in figure 1.

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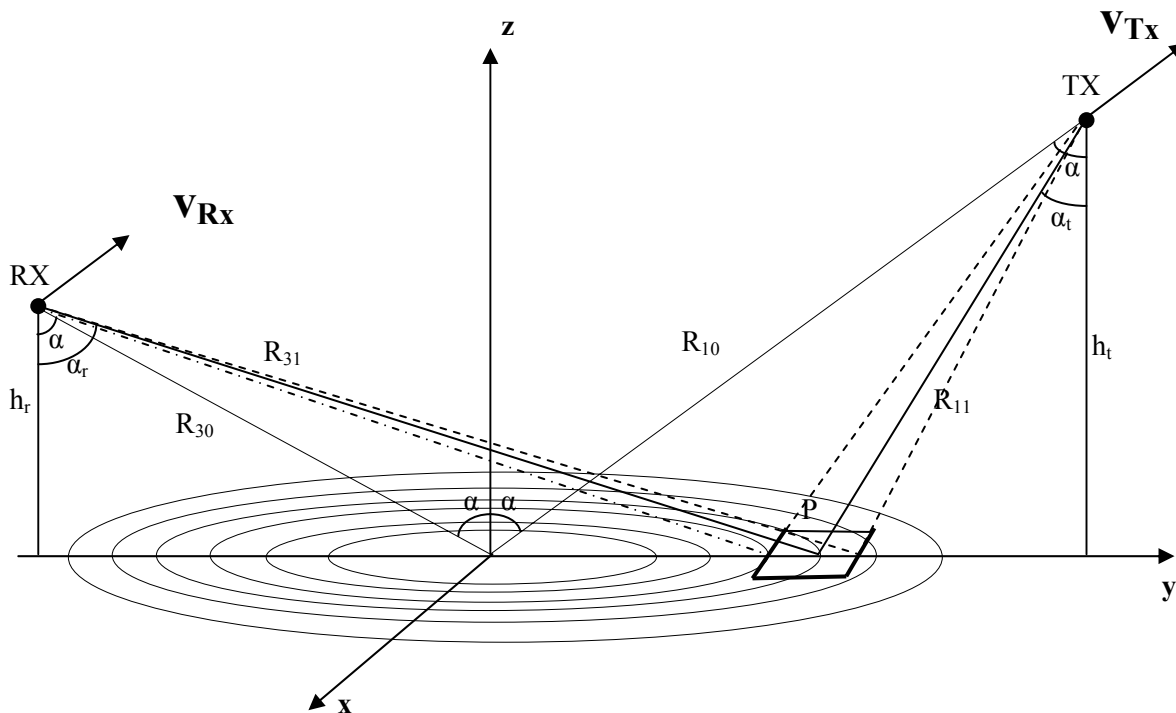


Figure 1

The satellite trajectories must be compensated in order to perform the synthetic aperture. The relation that considers the value of  $R_{30}$  in figure 1 must be modified when considering the radial component of the velocity. In order to choose the right centre of the swath, along the  $y$  axis, we can define the bistatic ellipse as the collection of points  $P$  so that the sum  $TP + PR$  is constant (where  $TP$  is the transmitter-point distance and  $PR$  is the point-receiver distance). If we consider two consecutive ellipses which cross the  $y$  axis in  $P_1$  and  $P_2$  respectively the difference  $\delta = (TP_2 + P_2R) - (TP_1 + P_1R)$  represents the bistatic range cell resolution in the slant plane. This distance, considered in the ground plane ( $x, y$  plane), is the distance between the two consecutive ellipses. Therefore, if  $P_1$  is placed in  $(0, y_1, 0)$ ,  $P_2$  will be in  $(0, y_1 + R_D, 0)$  where  $R_D$  is the range resolution. Moreover  $\delta$  is connected to the transmitted chirp bandwidth  $B$  by the relation

$\delta = \frac{c}{B}$ . We can calculate, after having imposed the range resolution  $R_D$ , the chirp bandwidth  $B$  as a function of the coordinate  $y_1$  for the center of the swath.

The figure 2 shows that, if we impose, for example, a range resolution of 500 m and a swath centered in  $y=700$  Km, we need a chirp bandwidth of about 1.2 MHz.

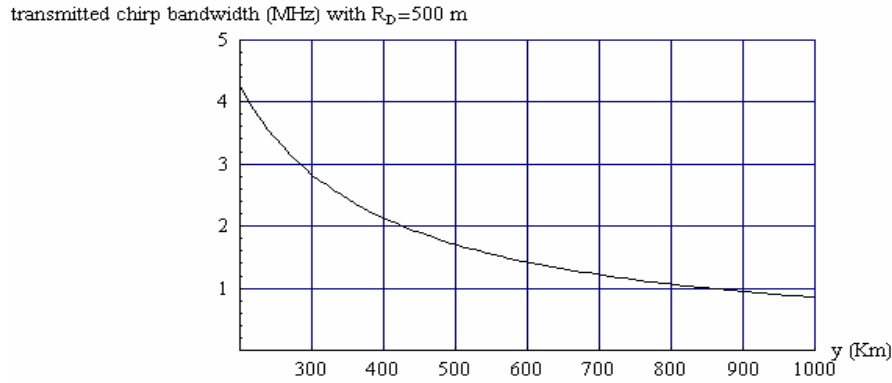


Figure 2

In order to evaluate the Doppler chirp we can write the frequency slope as [23]:

$$\frac{df}{dt} = \frac{B_A}{T_A} \rightarrow T_A = \frac{\lambda}{L_r} \frac{PR|_0}{V_{RX}} \quad (1)$$

where:

$$PR|_0 = PR|_{t=0, x=0} = \sqrt{[h_r \tan \alpha + y]^2 + h_r^2} \cong \frac{h_r}{\cos \alpha} + \frac{y^2 \cos^3 \alpha}{2h_r} + y \sin \alpha \quad (2)$$

The azimuth resolution is equal to:

$$R_{AZ} = \frac{V_{RX}}{B_A} \cong \frac{V_{RX}}{V_{RT}} L_r \quad (3)$$

and the integration gain is given by:

$$T_A = \frac{\lambda}{L_r V_{RX}} \frac{h_r}{\cos \alpha_{Pr}} \rightarrow B_A T_A = \frac{\lambda}{L_r^2} \frac{V_{RT}}{V_{RX}} \frac{h_r}{\cos \alpha_{Pr}} \quad (4)$$

where  $\alpha_r$  is shown in figure 1.

In order to avoid aliasing problem it is necessary that:

$$p.r.f. > B_A = \frac{df}{dt} T_A \cong \frac{V_{RT}}{L_r} \quad (5)$$

We can notice that the last approximations can be accepted in case of slow target motion.

#### 4. TARGET ENGAGEMENT

The **acquisition phase** is a continuous process (multiple target detection requirement) while the tracking process will start, after the detection, for each target.

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The signal to noise ratio for bistatic radar, after compression gain, can be written as:

$$SNR = \frac{P_p}{4\pi\lambda^2} A_t A_r \cdot \frac{\sigma \cdot \tau}{R_t^2 \cdot R_r^2 \cdot KTFL} \quad (6)$$

where:

$A_t$ ,  $A_r$  are the transmitter and receiver antenna area,  $\lambda$  is the wavelength of the transmitted frequency,  $R_t$ ,  $R_r$  are the range transmitter-target and receiver-target,  $\sigma$  is the target radar cross section,  $KTBF$  is the noise power and  $L$  is the system loss.

In order to obtain at least an SNR value of 12 dB, by the previous equation, we can calculate the pulse duration as shown in table 1.

**Table 1**

	f = 2 GHz		
Parameter	Value	dB	Note
Pp	75 kWatt	-48.7	
$\lambda^2$	(0.15) <sup>2</sup>	-16.5	Wavelength
K	1.38·10 <sup>-23</sup>	-228.6	Boltzman constant
T	300°K	24.7	Temperature °K
$A_t \bullet A_r$	(15•15) <sup>2</sup> m <sup>4</sup>	-47	Transmitter antenna area
F·L	2	3	Noise figure and loss
4π	12.56	11	
Σ	0.2 m <sup>2</sup>	6.98	Bistatic radar cross section
$R_r^2 = (hr/\cos\alpha_r)^2$	(1830) <sup>2</sup> Km <sup>2</sup>	125.2	$R_r = hr/\cos\alpha_r$
$R_t^2 = (ht/\cos\alpha_t)^2$	(4315) <sup>2</sup> Km <sup>2</sup>	132.7	$R_t = ht/\cos\alpha_t$
SNR		12	
T	3 ms	25	
$r > \sqrt{T \tau}$	> 7.5 m		Range resolution

It has to be considered that this ground resolution is enough for the detection (the requirement is a basket of 1°•1°•1 km).

The IF (improvement factor) for the clutter canceller has to reduce the clutter below the noise level and, at least, a double canceller is needed. An alternative solution is to limit the scanning to a surfaces that are positioned at a suitable height with reference to the ground surfaces.

Concerning the **Tracking** phase, we can notice that an advantage to use the SAR is the possibility to detect closely target within the required basket.

It is straightforward to conclude that the SAR technique produces a better on ground resolution and therefore reduces the needed clutter cancellation (improvement factor).

The CSR (Clutter to Signal Ratio) considering a locally homogeneous terrain is equal to:

$$CSR = \frac{\sigma^0 \cdot \delta_r \cdot \delta_{az}}{\sigma} \quad (7)$$

where  $\delta_r$  and  $\delta_{az}$  are respectively the range and azimuth resolution on the ground while  $\sigma^0$  (assumed equal to 0.01 for typical scenario) and  $\sigma$  are respectively the on ground backscattering coefficient and the target cross section.

Assuming the possibility to reach a value of CSR equal to -20 dB, by having a range and azimuth  $\delta_r$  and  $\delta_{az}$ , we can find out the necessary Improvement Factor(IF), as shown in Fig. 3.

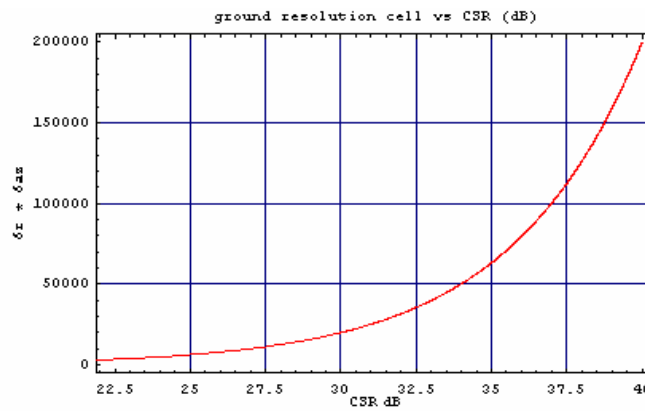


Figure 3

It is evident, by the figure, the resolution required in order to obtain a feasible IF. The design of the system is performed in order to initialize the tracking only on the detected targets during the acquisition phase. In this way the system is operating simultaneously a continuous search and a tracking.

The tracking process can be improved by the utilization of the SCANSAR technique. In this way it is possible to track the target, also in presence of an heavy fading, once an estimation of the target trajectory has been obtained by the detection process.

Moreover by geometric manipulations we obtain [23]:

$$L_r > \frac{V_{RT} S_R^2 \cos^3 \alpha}{\gamma 2 H c} \Leftrightarrow S_R^2 = y_{\max}^2 - y_{\min}^2 \Leftrightarrow \Delta_R = y_{\max} - y_{\min} \quad (8)$$

$$\Delta_R = \frac{\lambda}{b_r} \frac{h_r}{\cos^2 \alpha} \Rightarrow b_r = \lambda \frac{h_r}{\Delta_R \cos^2 \alpha} \quad (9)$$

By the equation (8) appears that swath dimension  $S_R$  and resolution  $\Delta_R$  are strictly related and in order to increase the dimension of the swath a large dimension of physical antenna is required; the limitation on swath dimension is a major problem considering the required large dimension of the coverage area. The dimension of the real antenna imposes constraints on swath dimension and its maximum permissible dimensions longitudinal (cross track) and transversal (along track) must satisfy the eq.s (8) and (9). In order to cover an access area of 1500\*1500 Km<sup>2</sup> the SCANSAR technique divides the whole area in a

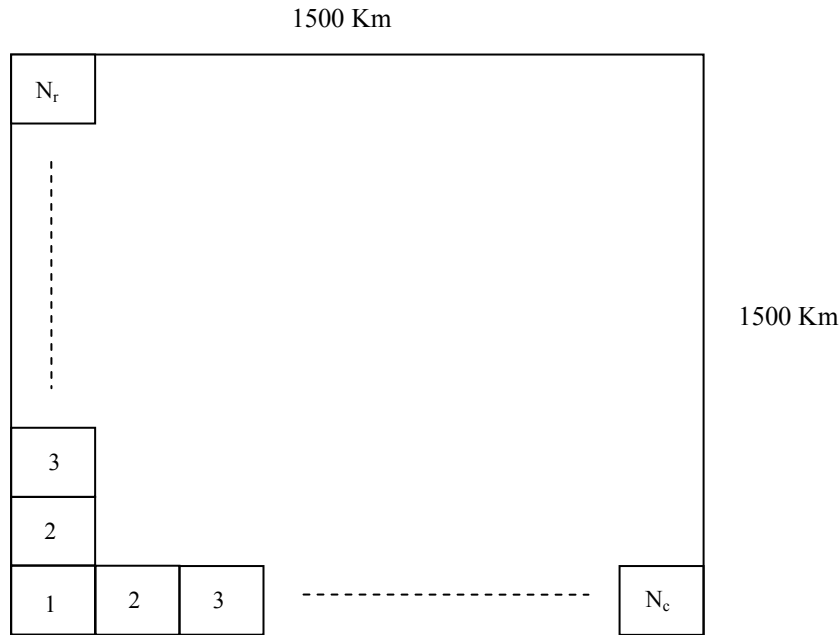


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number of sub-swaths  $N_r * N_c$ . The constraint that the access area  $A_q$  will be completely covered during the satellite trajectory is defined by:

$$A_q = (1500)^2 \text{ Km}^2 \rightarrow T_A N_r N_c \leq 1500 \text{ Km} / V_{RX} = 200 \text{ sec} \quad (10)$$

where  $N_r$  and  $N_c$  are the number of vertical and horizontal sub-swaths necessary to cover the access area (see Fig.4) and  $T_A$  is the acquisition time necessary to obtain a SAR image of one sub-swath.



**Figure 4**

To evaluate  $T_A$  we have to consider that the maximum time available in order to avoid the target migration outside the SAR resolution cell, within two pulse repetition interval (minimum condition necessary to perform a suitable clutter cancellation), is equal to:

$$T_a = \frac{R_{AZ}}{2v_T} \quad (11)$$

where  $v_T$  is the target velocity.  $T_a$  is the maximum time available to obtain the SAR image. The SAR resolution is given by:

$$R_{AZ} = \frac{V_{RX}}{B_A} = \frac{V_{RX}}{V_{RT}} L_r \quad (12)$$

where  $V_{RX}$  is the receiver velocity and  $B_A$  is the Doppler chirp bandwidth defined by equation (5).

The time necessary to obtain the SAR synthetic aperture is equal to:

$$T_A = \frac{\lambda}{L_r} \frac{h_r}{\cos \alpha_{Pr}} \frac{1}{V_{RX}} \quad (13)$$

Imposing  $T_a = T_A$  we obtain the real antenna dimension:

$$\frac{R_{AZ}}{2v_T} = \frac{V_{RX}}{2v_T V_{RT}} L_r = \frac{\lambda}{L_r \cos \alpha_{Pr}} \frac{I}{V_{RX}} \rightarrow L_r^2 = \frac{\lambda}{V_{RX}^2} \frac{h_r}{\cos \alpha_{Pr}} V_{RT} 2v_T \quad (430)^2 m^2 \rightarrow L_r \quad 430m \quad (14)$$

where  $V_{RT}$  is the LEO satellite velocity equal to 7.6 Km/s.

This states that it's impossible to perform an usual SAR processing which use the whole synthetic aperture. So we have to use a synthetic sub-aperture which is a fraction (equal to  $1/N_L$ ) of the maximum permitted synthetic aperture length and follows that:

$$R_{AZ} = \frac{V_{RX}}{B_A} N_L = \frac{V_{RX}}{V_{RT}} L_r N_L \quad (15)$$

$$\frac{T_A}{N_L} = \frac{\lambda}{L_r N_L \cos \alpha_{Pr}} \frac{I}{V_{RX}} \quad (16)$$

The equation (13), considering the equation (16) becomes:

$$T_a = \frac{T_A}{N_L} \rightarrow (L_r N_L)^2 = \frac{\lambda}{V_{RX}^2} \frac{h_r}{\cos \alpha_{Pr}} V_{RT} 2v_T = (430)^2 m^2 \rightarrow L_r N_L = 430 m \quad (17)$$

In this way the number of sub-aperture  $N_L$  in which the synthetic antenna is divided can be chosen so that we can obtain a feasible antenna dimension  $L_r$ .

Therefore the maximum permissible value of the azimuth resolution is:

$$R_{AZ} = \frac{V_{RX}}{V_{RT}} L_r N_L \cong 425 m \quad (18)$$

In this case the synthetic sub-aperture is equal to:

$$L_s = \frac{\lambda}{L_r N_L \cos \alpha_{Pr}} \quad 640 m \quad (19)$$

With the assumption in (17) the value of  $T_a$  becomes:

$$T_a = \frac{T_A}{N_L} = \frac{R_{AZ}}{2v_T} = 0.085 s \quad (20)$$

The number of sub-swaths is given by:

$$T_a N_r N_c \leq 200 \text{ sec} \rightarrow N_r N_c \leq \frac{200 \text{ sec}}{T_a} \cong 2353 \quad (21)$$

The transmitter swath must be greater than receiver swath for practical reasons and to verify this condition, as an example, the maximum possible value for antenna dimension are:

$$A_t = 15 \quad 15 = 225 m^2 \rightarrow S_p^t = \frac{\lambda^2 h_t^2}{A_t \cos^3 \alpha_{Pt}} \quad 2000 \text{ Km}^2 \quad (22)$$

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In order to satisfy the above constraint  $A_r = L_r b_r \leq 120 m^2$ , we can choose, in order to obtain an approximately square swath,  $L_r = 11 m$ ,  $b_r = 11 m$ , then  $N_L$  is:

$$L_r N_L = 430 m \rightarrow N_L \cong 39 \quad (23)$$

So we can consider only 1/39 of the whole synthetic aperture. With this value we obtain the stated resolution of 425 m.

The azimuth compression gain is defined as the number of pulses integrated in the acquisition time  $T_a = \frac{T_A}{N_L}$  and then it can be written as  $p.r.f. \cdot T_a$ .

The clutter requirements imposes to maintain the swath as small as possible.

The time required to cover the access area is 200 sec, and potential targets launched during the acquisition and tracking time can not be detected unless several LEO are utilized. In order to overcome this problem, if a preliminary information, on possible launch sites, is available, the acquisition and tracking can be focused only on these sites. In this case the coverage percentage can be increased and simultaneously will also increase the probability to discover simultaneous threats, differently located, in the access area.

## 5. CLUTTER EVALUATION

If we accept to detect the threat at a certain altitude we can consider that the transmitter and the receiver are not pointed on the ground but at a particular height. Therefore the swaths on the ground are not in the same location and then the influence of the clutter could be reduced (if the two swaths are not overlapped, the clutter will be absent, at least in the main lobe) (see Fig.5).

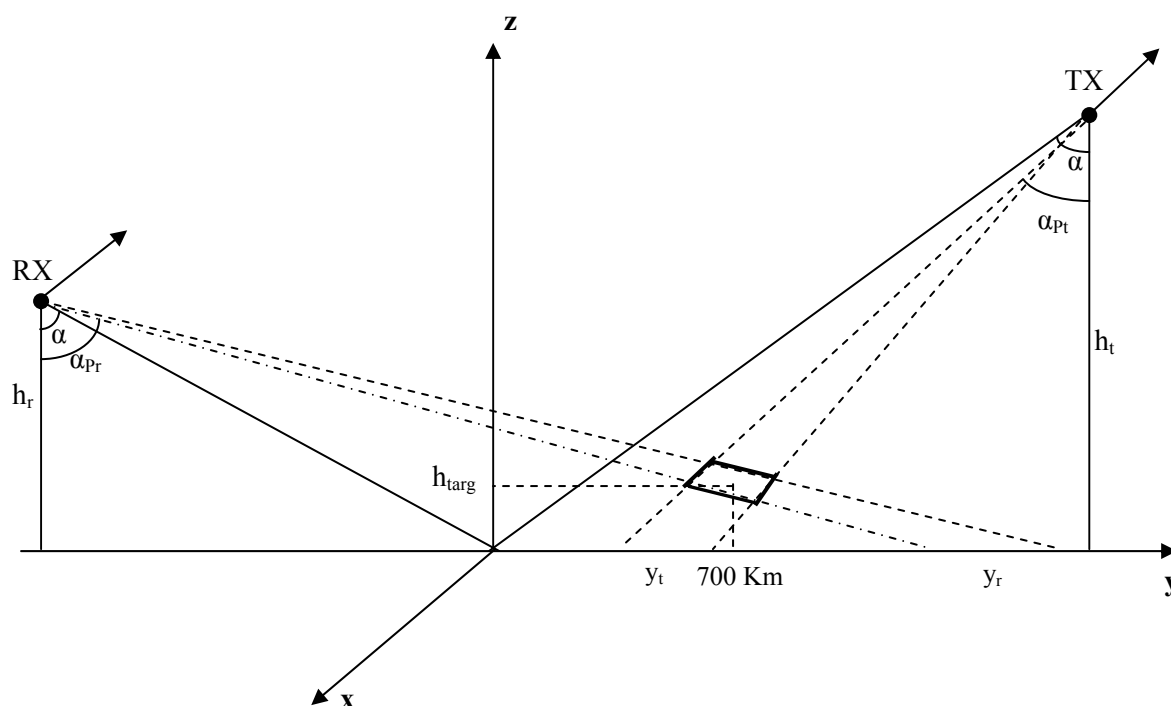


Figure 5

In order to avoid the clutter in the main lobe of the receiver we have to point the antennas at a higher altitude.

It has to be highlighted that to avoid the constraint that the target will be detected only at very high height we can reduce the receiver swath increasing the receiver antenna area up to 225 m<sup>2</sup> (presently has been fixed at 120m<sup>2</sup>). This constrains can only be removed if we reduce the access area.

When utilizing clutter canceller the Moving Point Object (MPO) detection and velocity estimation can be performed either incoherently, with a single SAR aperture, or coherently, with two or more apertures [20].

If the receiver antenna is partitioned in two apertures along track direction, coherent processing can be used to find moving objects and estimate their velocities.

The fundamental principle is that each aperture (phase centre) observes the scene from the same point in space at a different time. Features whose range location has shifted from one scene to the next are moving-target candidates. SAR data from each aperture are focused to a complex image and the image content is common except for scene changes over time  $\tau$ . For land scenes “fixed” elements are stationary over time  $\tau$  and their images will be very nearly identical.

Moving objects will be displaced between the two scenes, and these displacements can be measured as phase shifts: **Displaced Phase Centre Antenna (DPCA)**.

The SAR DPCA analysis is made by the correlation between the complex sample sets of the first aperture image,  $S_1$ , and the second aperture image,  $S_2$ , to yield:

$$J = S_1 - S_2 = |S| \cdot (e^{j\phi_1} - e^{j\phi_2})$$

$$J = 2 |S_1| \sin \left( \frac{\phi_1 - \phi_2}{2} \right) e^{j \left( \frac{\phi_1 + \phi_2}{2} + \frac{\pi}{2} \right)} \quad (23)$$

The magnitude of the subtracted DPCA signals is a sinusoidal function, whose argument is directly proportional to the speed  $v_{\text{targ}}$  of the scene elements. Transfer function of the DPCA canceller is given by [22]:

$$|H(f, \theta)|^2 = \left[ 1 + \tan^2 \left( \frac{\eta}{2} \right) \right] \cdot \left[ 2 \cdot \sin \left( \pi \frac{f - f_d}{f_r} \right) \right]^2 \quad (24)$$

The performance of the moving target indication with DPCA are shown in [22].

## 6. CONCLUSIONS

The satisfaction of the main requirements can be obtained with a Bistatic configuration utilizing the phase array technology. The use of BSAR permits to increase the resolution and discriminate closely targets. The preliminary study shows that the bistatic solution is a good trade off for the feasibility of the system. The availability of the satellites on the theatre is a function of the number of satellite within the LEO and HEO/GEO constellation. The transmitted power needs to be very high, for the given SNR (low target RCS), and its value can be obtained by summing the power of more than one HEO satellite. The orbit selection, when operating with BSAR must be selected accurately in order to intercept the target according to the necessary geometry.

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## Bistatic Space Borne Radar for Early Warning



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*Symposium on*

**"Integration of Space-based Assets  
Within Full Spectrum Operations"**

# **Bistatic Space Borne Radar for Early Warning**

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# Scenario

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- Geo-political evolution of recent years has changed balance set up worldwide from Cold War era.
- Ethnic-cultural-religious movements have pushed towards claims not canalised within democratic processes. Pressures have been generated to western world, giving rise to origin of movements with terrorist ends and hostile country too.
- Crush down of eastern world and economic powers has spread out knowledge, developments and re-cycling of old armaments.
- Risk of potential attacks to Europe or against European forces out of the continent has increased.
- Awareness of importance of ballistic missile defence has set up. In particular Regional Early Warning System study in Europe is going to be assessed.

# Why Space Assets ?

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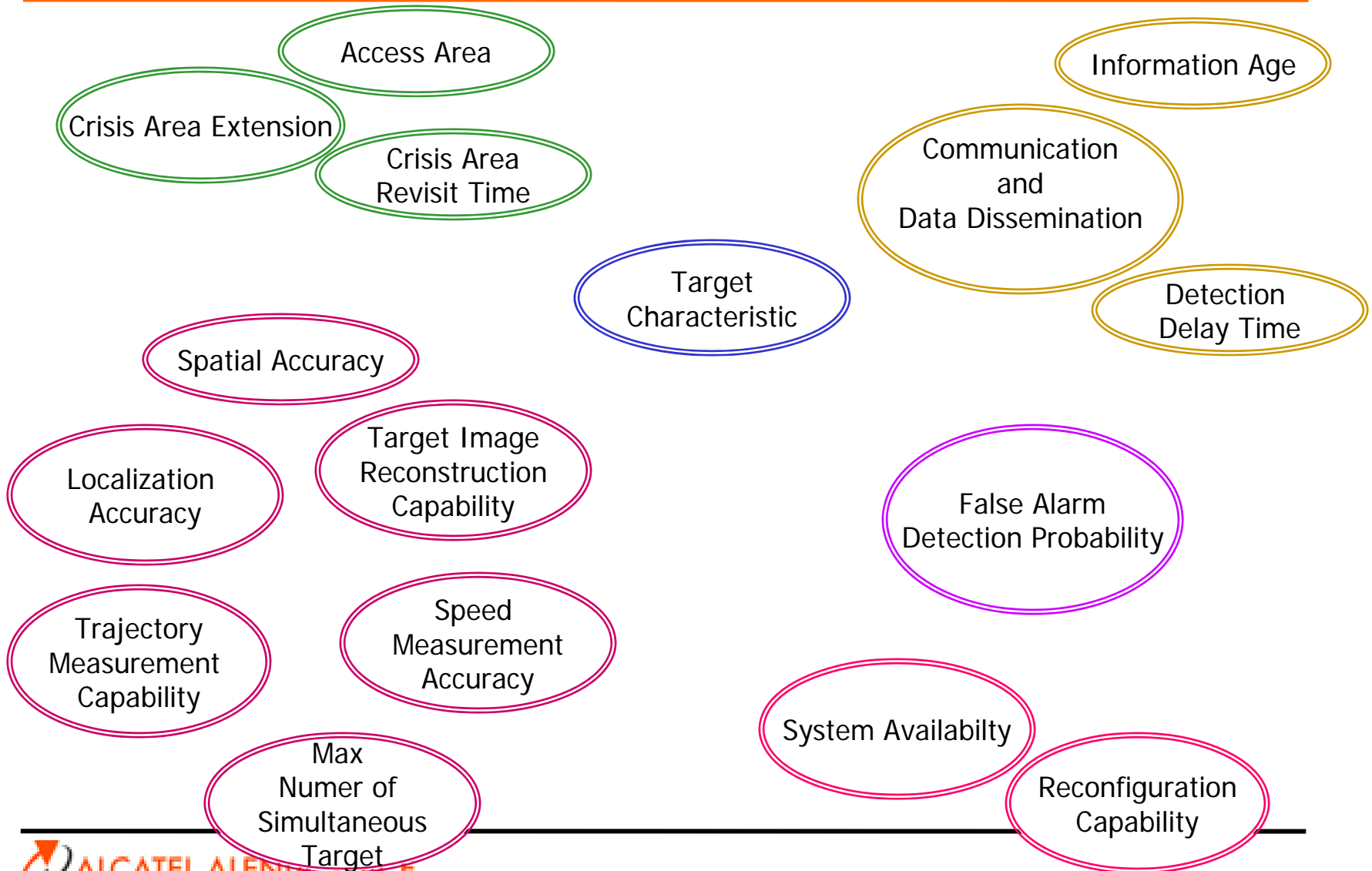
- Difficult to jam. It is difficult to jam its capabilities.
- User Premises Services. Small earth stations with small antennas can provide access to databases, branch offices, and management information systems.
- Continuous operability.
- Wideband Capability. Satellite repeaters are usually wideband devices that can transmit large amounts of information. Tens of megahertz of bandwidth are available in each repeater.
- Broad Coverage. Technically, it can serve any type of station in view of its antenna.
- Better Coverage of Rural and Undeveloped Areas. It can provide the same type of service in every situation.
- New Services. It can provide the merging of different types of data to better exploit event information.

# Needs for Missile Defence

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- Theatre area surveillance within a wide area surveillance coverage.
- Continuous coverage (or very low percentage of gap).
- Engagement of the threats (detection, plot and track) within a theatre area.
- Estimation of launch point.
- Estimation of final impact point (target) of the threat.
- Delivery of the threats kinematics characteristic, within a defined basket, to the ground based radar for the immediate defence reaction.
- Identification and classification of the threat.
- System architecture based on multiple-sensor (IR and EM) capabilities and data fusion.

# Driver Parameters



# Available Warning Systems Technologies

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Sensor Trade-off for Missile Defence Applications are on:

- INFRARED

Thermal IR instrument is capable in missile detection during boost phase. It suffers from weather conditions.

- MICROWAVE

Radar instrument is less sensitive to weather conditions. Due to clutter, detection of missile in the boost phase can be difficult. Radar sensor is capable to provide good and accurate tracking.

- UV-VIS

They can be used in the surveillance for supporting intelligence activities. They suffer from weather conditions.

In all of the three types of target, identification capability can be based on their spectral signature.

# Space Borne Radar for Early Warning

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- This study is addressed to analyze the requirements and a proper design of a space borne Bistatic SAR (BSAR) with the relevant performance. The bistatic solution has been considered as a preferred one due to the good immunity to potential jammer present on the theatre area, allowing also a reduced value of peak transmitter power, permitting to utilize quite all the temporal interval for the signal transmission without interruption during the receiving phase. The BSAR technique permits to increase the resolution in order to discriminate closely targets.
- In addition it has been investigated the imaging of an isolated fast moving pointing object (MPO) and the clutter cancellation needed in presence of fixed terrain/sea background (feature expected in the realistic situation of an object moving over a terrain or over the ocean).

# Reference Requirements - System

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- Minimum Target RCS  $0.2 \text{ m}^2$
- Radar Cross Section will fluctuate according to Swerling case 1;
- Altitude within 50 Km- 400 Km for TBM, 200 m- 400 m for cruise missile (option) and 200 m- 10 Km for aircraft;
- Maximum range for TBM 3500 km;
- Time of flight for TBM  $< 15$  minutes;
- Average absolute velocity for TBM  $\leq 2.5 \text{ km/sec}$  ;
- Delivery of the target position within a basket of  $1^\circ \bullet 1^\circ \bullet 1 \text{ km}$ . In case of tracking on board (plot association, track formation) the resolution (discrimination of closely target) must be within 1 km;
- Jamming present on board enemy aircraft and on enemy ground based radar.
- Presence of Ground/Sea clutter;

# Trade-off Activities

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Three configurations have been preliminary considered and envisaged as potential candidates for a design baseline:

- Transmitter on board heo satellite and receiver only on board the satellite constellation.
- Transmitter and receiver on board each satellite on the constellation.
- Monostatic solution.

First solution was chosen because of good immunity to potential jamming and reduced complexity of constellation.

Drawback is the range between the transmitter and the illuminated target and the required synchronization. In addition, a direct communication link between the transmitter and the receiver is necessary.

Major constraint on the system configuration (radar and satellite constellation) is the minimization of number of satellites. Such minimization may be provided by use of ScanSAR techniques.



# Challenges & Basic Constraints

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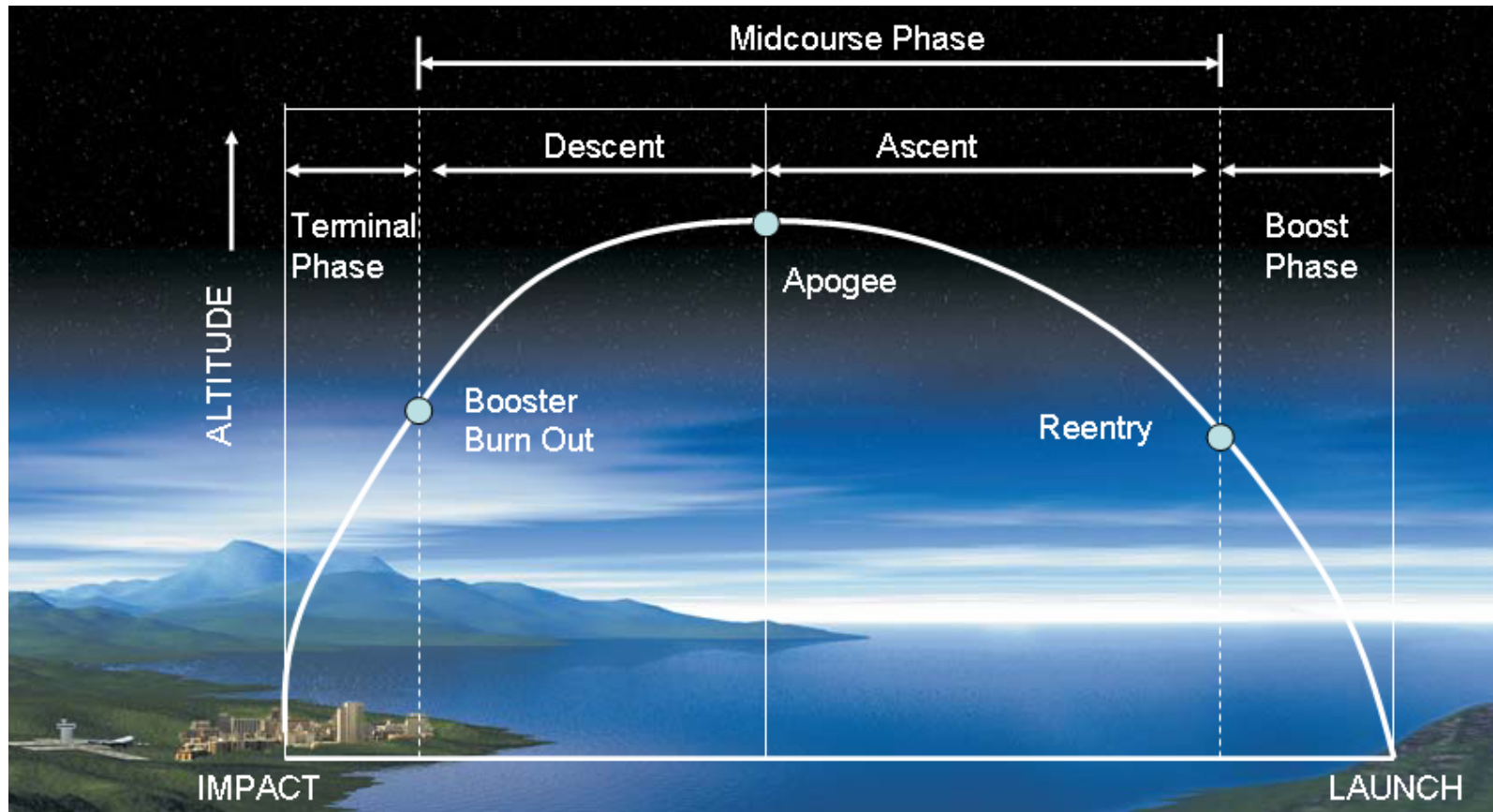
Major challenges related to traded-off solution are:

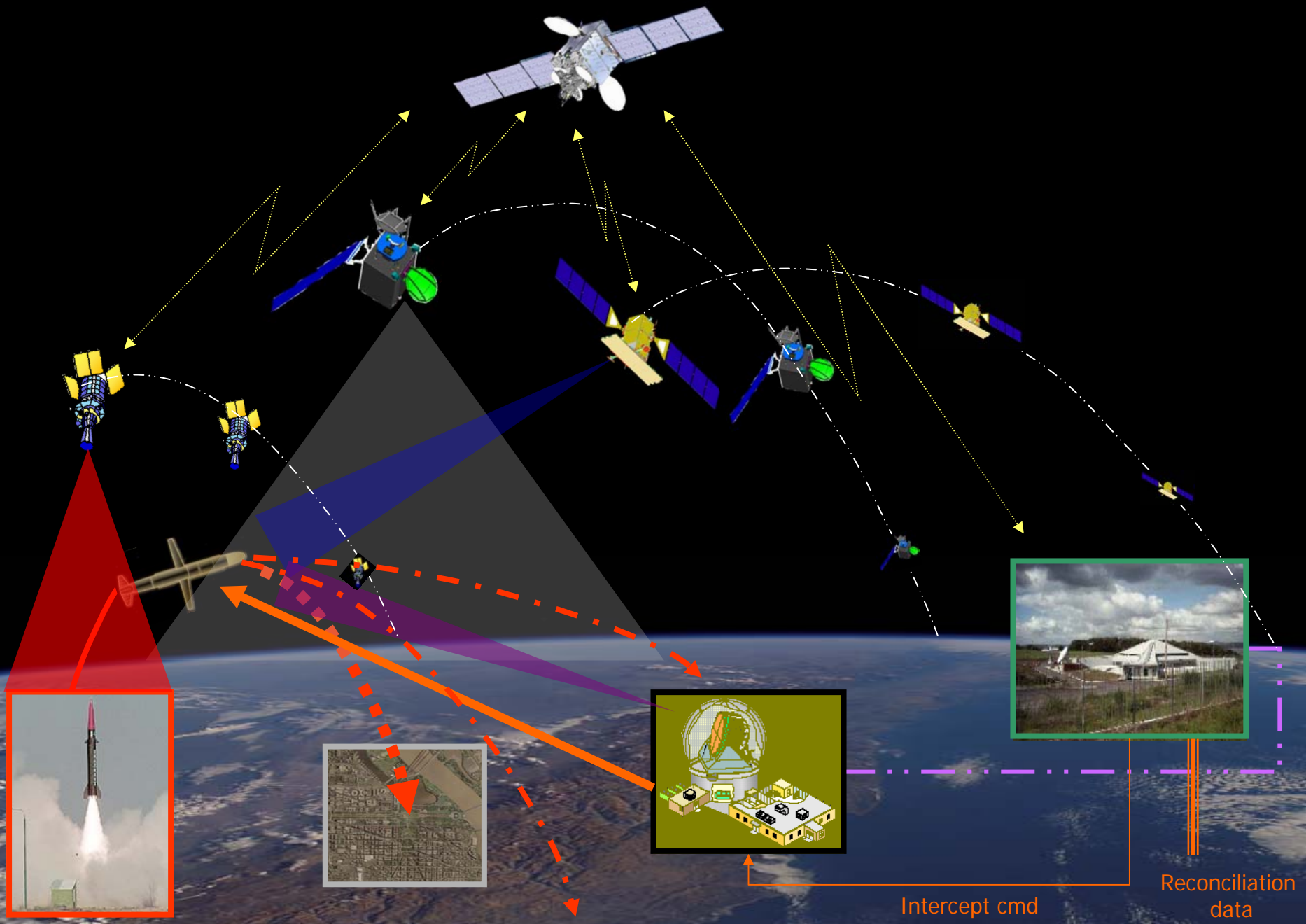
- Large number of SATS (small sats shall be employed for the constellation).
- Lightweight MW instruments.
- High power needed by the Tx apparatus on board HEO satellites.
- Constellation synchronization.
- Interoperability and information management.

In order to achieve a feasible solution, few constraints have been assumed, considering the present and future (next 10 years) state of the art technology:

- The maximum available transmitting power cannot be greater than 75 KW for practical reasons.
- The antenna dimension should be limited to 15 m  $\times$  15 m.
- A frequency utilization within the L band (1÷2 GHz) has been selected as a good trade-off between loss and components availability (antenna and transmitter).

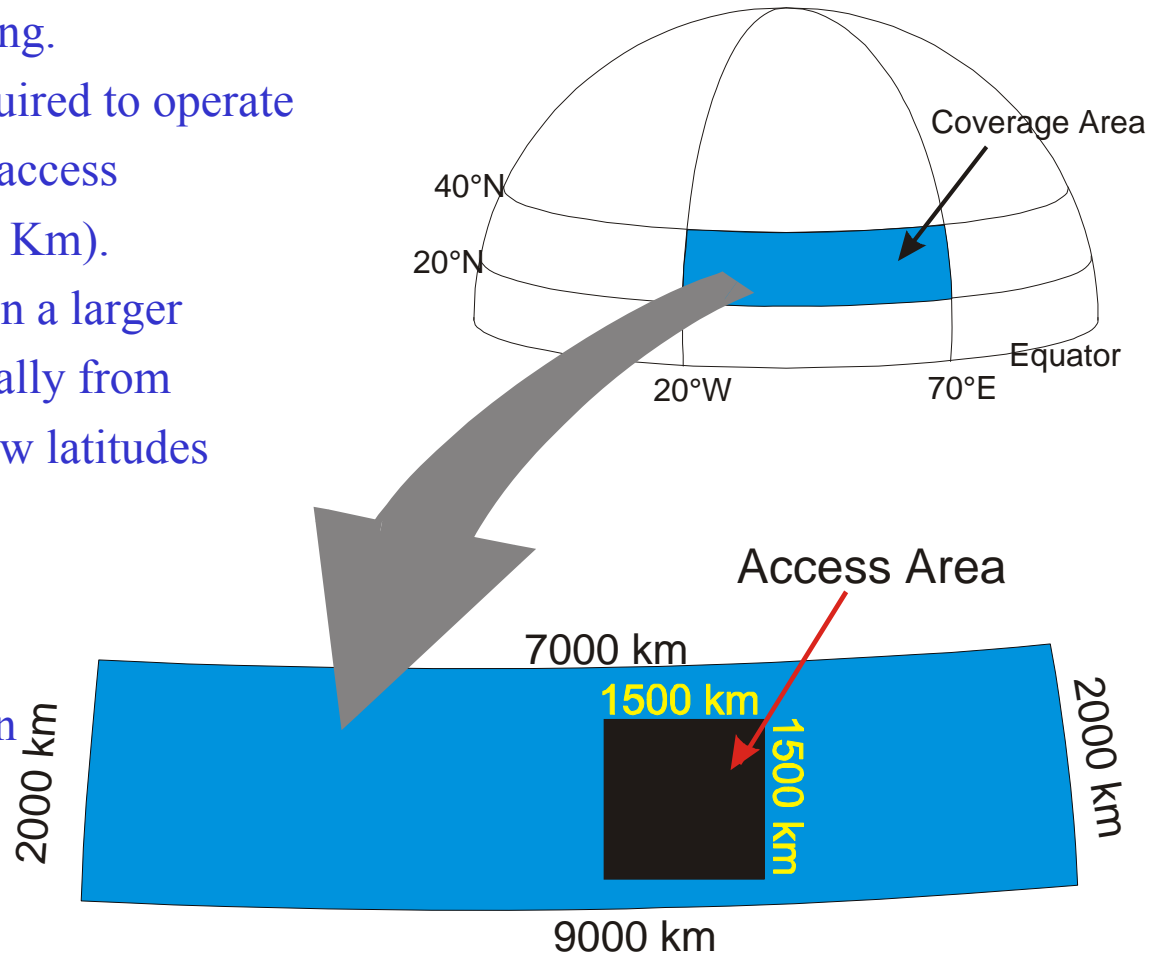
# Typical Missile Trajectory





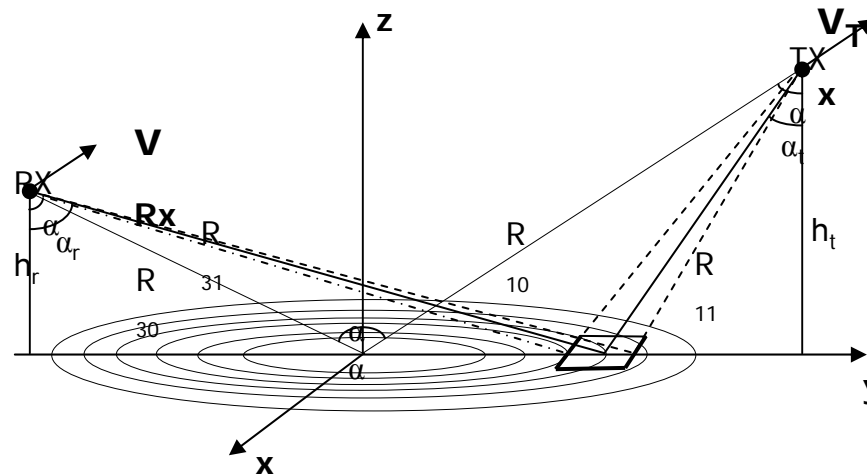
# SBREW Requirements - Observation

- The objective is to define a system able to alert defense countermeasures through proper target detection and tracking.
- The Early Warning system is required to operate over a square-shaped area called access area (Nominally 1500 km x 1500 Km).
- Access area can be selected within a larger area called coverage area (nominally from Atlantic to Indian ocean and at low latitudes above the equator).
- Continuous observation of the access area must be guaranteed with a minimum time lag between successive observations and compatible with the threat characteristics.



# SBREW Design (bistatic constraints)

- The targets for which the sum of distances with the two antennas is constant, cannot be resolved in range by the bistatic system. The positions of these targets located on the surface constitute an ellipse (“isorange contour”)
- It has to be highlighted that the trajectories of Rx and Tx can be positioned in any direction. Furthermore, due to Rx circular orbit and Tx elliptic orbit, there is a radial velocity component that is necessary to be compensated (only during the tracking phase). There are two extreme cases:
  - Rx and Tx trajectories are parallel and directed orthogonally to the drawing (assumption made in the paper).
  - Rx and Tx trajectories are in the same plane and each one is directed toward the other.



# Engagement & Tracking

The target engagement includes the following phases:

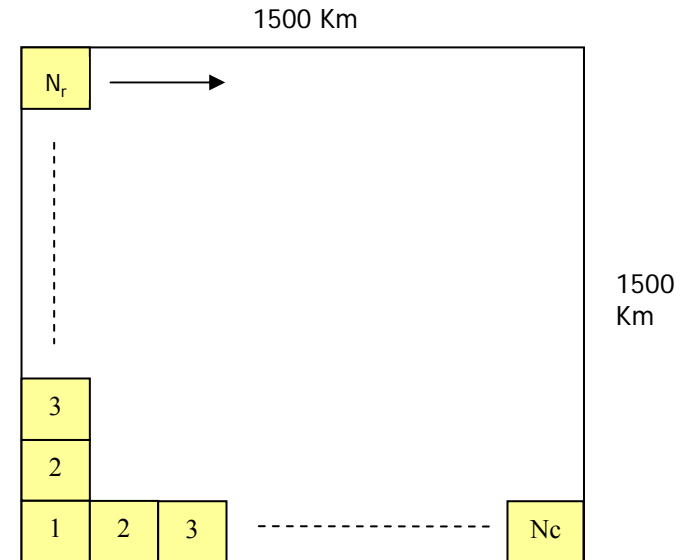
- Target acquisition (only detection while plot and track extraction will be performed by the on ground radar).
- Delivery to a ground radar of the static and cinematic parameters for a fast reaction.

The acquisition phase is a continuous process (multiple target detection requirement) while the tracking process will start, after the detection, for each target.

One of the objectives is to discriminate two or more targets inside one resolution cell during acquisition phase. This can be done by synthetic aperture radars.

Tracking process is implemented through synthetic aperture technique. In order to keep antenna dimensions into reasonable values, a multilook technique shall be adopted.

To cover the whole theatre area, with an acceptable resolution, ScanSar technique is implemented.



# Engagement & Tracking

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- The range compression gain can be written as  $B\tau$  where  $B$  is the transmitted chirp bandwidth (the same on which the noise power is evaluated) and  $\tau$  is the pulse duration. Therefore after range compression we obtain:

$$SNR = \frac{P_p}{4\pi\lambda^2} A_t A_r \cdot \frac{\sigma \cdot \tau}{R_t^2 \cdot R_r^2 \cdot KTFL}$$

- Once fixed the system geometry and architecture, pulse width may be dimensioned according to desired SNR.
- In order to avoid the clutter in the main lobe of the receiver antenna we can point the antennas at a higher altitude.
- Moving objects will be displaced between the two scenes and these displacements can be measured as phase shifts.

# Conclusions

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- The baseline solution, that suggests the best trade off performance feasibility, is a bistatic solution (presence of jammer on enemy radar) with the transmitters on HEO/GEO and the receivers on LEO constellation (on board LEO only receiver and on board HEO/GEO only transmitter). The Phased Array technology shall be applied.
- By the system point of view the task of the early warning process is the target engagement that can be divided into acquisition and tracking.
- The detection process will be performed on a single (or multiple when possible according to the scanning time of the theatre area) spot basis due to the absence of information on the target trajectory. The tracking process will follow the detection on a SAR basis, in order to increase the resolution, being possible the estimation of the target trajectory and therefore the processing with a suitable selection of dedicated filters.
- For the satisfaction of the system requirements the tracking is not required due to the assumed value of the antenna dimension. The tracking phase (SAR) is a good option for the discrimination of closely spaced targets.



# Conclusions

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- The Signal to Noise ratio (SNR) is a critical parameter, considering the satellites geometry (range) and the limited value of targets radar cross sections. Furthermore, the SNR is strongly related to the power density on the target and therefore to the swath dimension (TX and RX antennas gain).
- The theatre area is too much extended to be covered with a small number of satellites.
- Resolution requirements, for the target spatial identification, are in good agreement with the beam dimension during acquisition and also during tracking, due to the improvement factor, related to the implementation of the Synthetic Aperture concept (SAR), taking into account the integration of a certain number of pulses (defined by the time needed to generate the synthetic antenna referred to the PRF).
- The high transmitter power is definitely a heavy constraint as well as antenna dimensions.